



# Comparison

Machine Reference Points  
 $y$  = Machine Centre  
 $x$  = Front Wheel  
 $w$  = Rear Wheel

Distances where  
 visibility lines intersect  
 machine reference lines  
 $A = 6.90\text{m}$   
 $B = 2.65\text{m}$   
 $C = 0.77\text{m}$

Area of ultra sonic  
 detection



$\square = 0.5\text{m}$



Area of vision  
 through rear camera system