

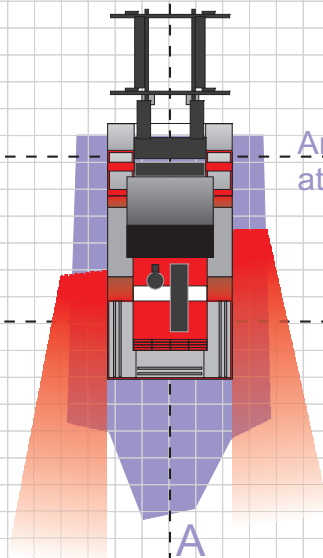


Kalmar DCD100

Machine Vision

Machine Reference Points
 y = Machine Centre
 x = Front Wheels
 w = Rear Wheels

Distances where
 blind spot areas intersect
 machine reference lines
 A=2.5m



Area of blind spot
 at 1 metre high

Visibility through
 standard mirror

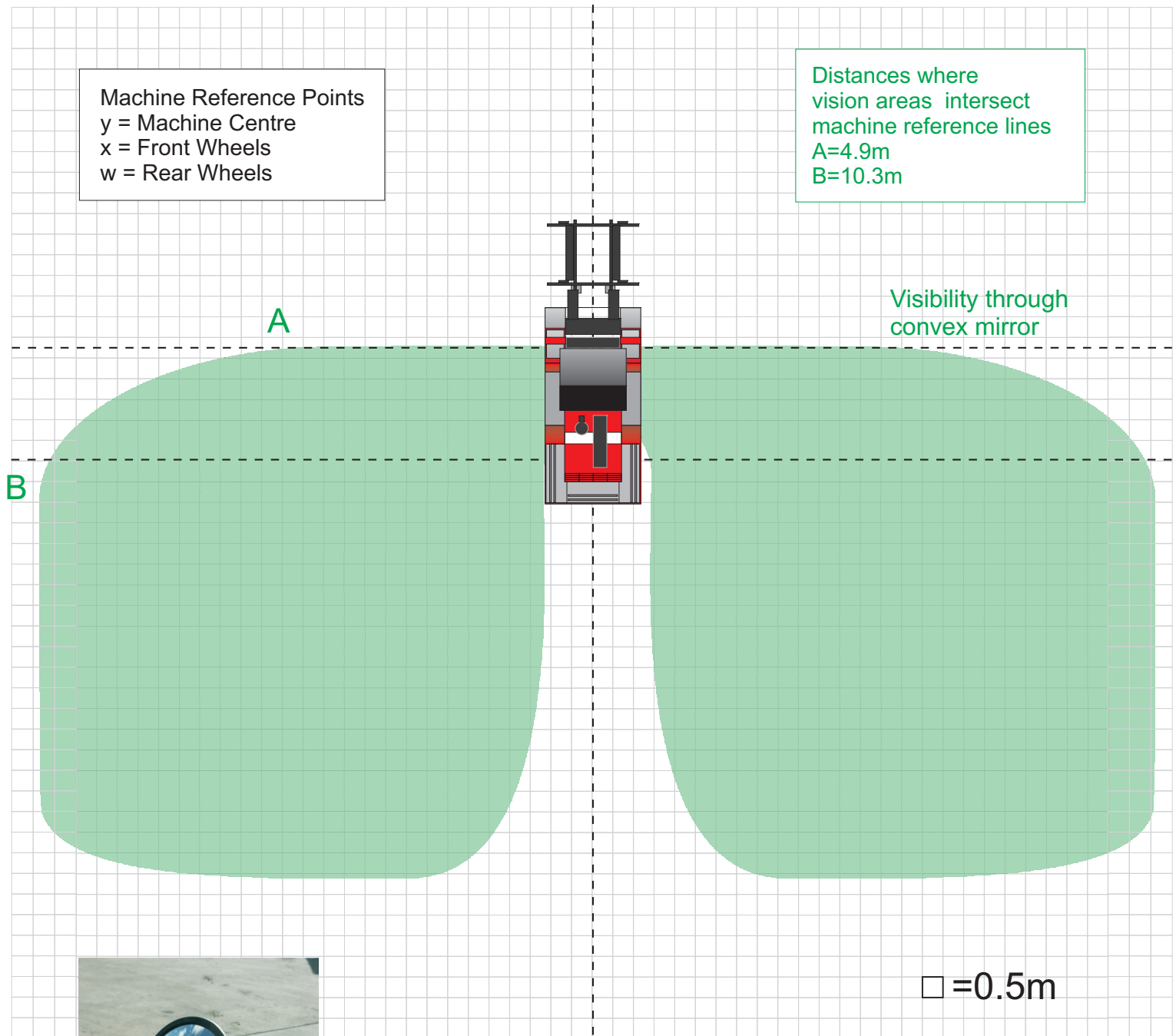


□ = 0.5m



Kalmar DCD100

Enhanced Vision Convex Mirrors





Kalmar DCD100

Enhanced Vision Camera/Radar

Machine Reference Points
y = Machine Centre
x = Front Wheels
w = Rear Wheels

Visibility through
rear view camera

Radar Area



□ = 0.5m



Kalmar DCD100

Enhanced Vision Convex Mirrors

□ = 0.5m

Machine Reference Points
y = Machine Centre
x = Front Wheels
w = Rear Wheels

Visibility through
convex mirror

Visibility through
standard mirror

Visibility through
rear view camera

