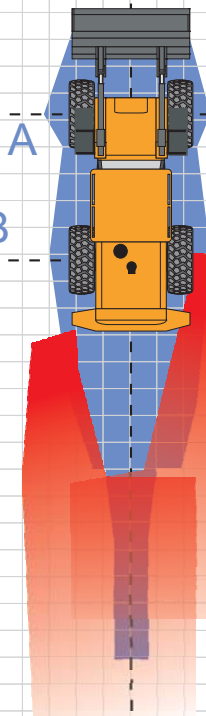# Machine Visibility

JCB 416

Machine Reference Points
y = Machine Centre
x = Front Wheel Centre
w = Rear Wheel Centre

Distances where
visibility lines intersect
machine reference lines
A=0.70m
B=0.40m
C=2.67m

y

x

A

w

B

Area of blind spot
at 1metre high

C

Visibility through
standard mirrors
at 1metre high

□ =0.5m

SPILLARD
safety systems

Enhanced Visibility

JCB 416

Machine Reference Points
y = Machine Centre
x = Front Wheel Centre
w = Rear Wheel Centre

y

x

w

Visibility through
Convex Mirrors
at 1metre high

□ =0.5m

Visibility through
camera system
at 1metre high

SPILLARD
safety systems

Comparision

JCB 416

Machine Reference Points
y = Machine Centre
x = Front Wheel Centre
w = Rear Wheel Centre

Distances where
visibility lines intersect
machine reference lines
A=0.70m
B=0.40m
C=2.67m

y

Area of blind spot
at 1metre high
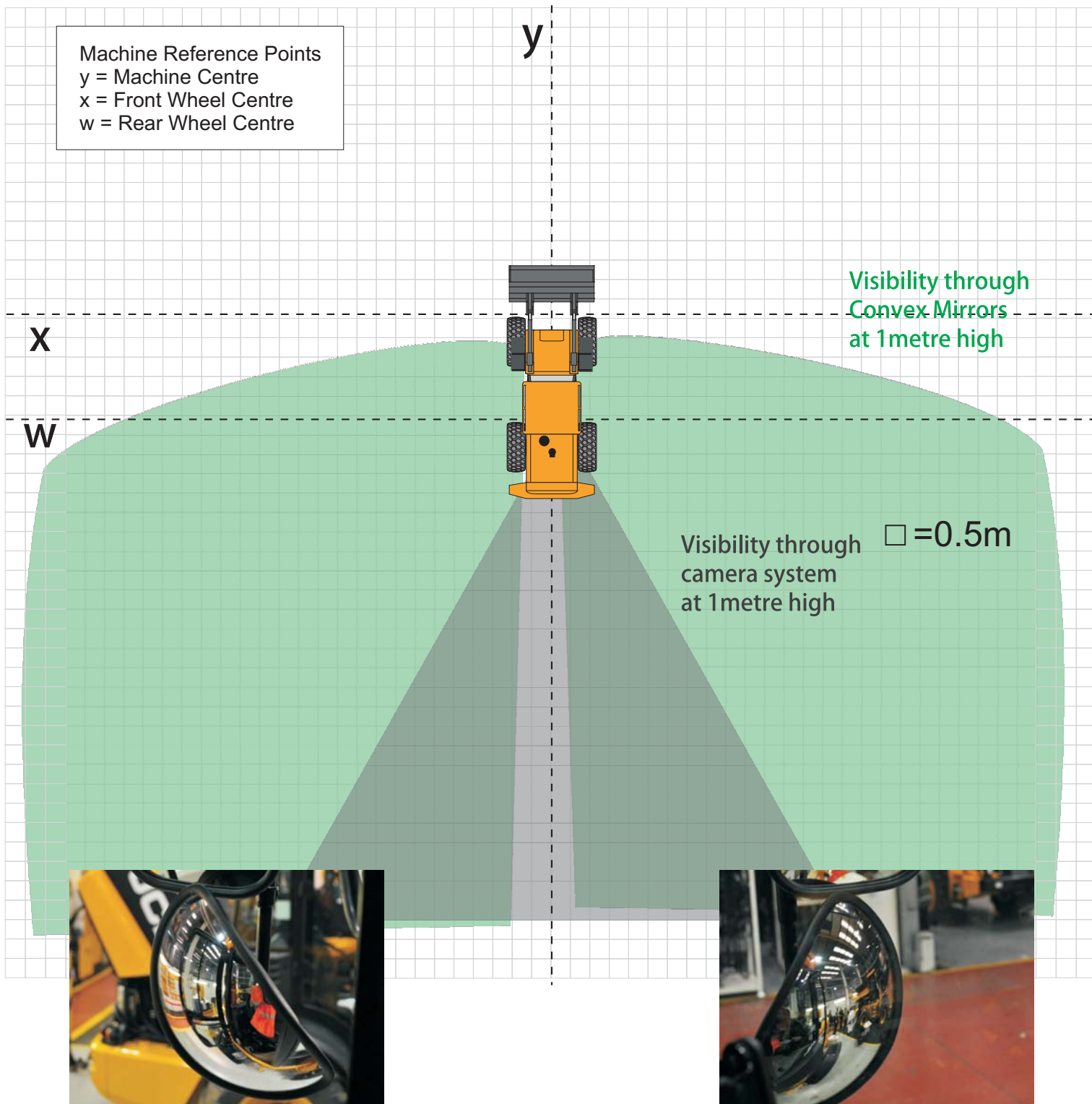
Visibility through
Convex Mirrors
at 1metre high

x

w

Visibility through
standard mirrors
at 1metre high

Visibility through
camera system
at 1metre high

□=0.5m

SPILLARD
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